# **GETRIEBEBAU NORD**

Member of the NORD DRIVESYSTEMS Group



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SK CU4-ETH Part number: 275 271 027

#### Industrial Ethernet - Internal bus interface 1)

 With NORDAC LINK, Industrial Ethernet is factory-fitted as a purchased option and configured according to customer specifications. Retrofitting is not possible.

The bus interface may only be installed and commissioned by qualified electricians. An electrician is a person who, because of their technical training and experience, has sufficient knowledge with regard to

- Switching on, switching off, isolating, earthing and marking power circuits and devices,
- Proper maintenance and use of protective devices in accordance with defined safety standards.

# **A** DANGER

#### Danger of electric shock

The frequency inverter carries hazardous voltage for up to 5 minutes after being switched off.

• Work must not be carried out unless the frequency inverter has been disconnected from the voltage and at least 5 minutes has elapsed since the mains was switched off.

#### Validity of document

This document is only valid in conjunction with the operating instructions of the respective frequency inverter and the bus communication manual for this bus interface ( See overview at end of document). These documents contain all of the information that is required for safe commissioning of the bus interface module and the frequency inverter.

#### Scope of delivery

1 x	Bus interface	SK CU4-ETH
1 x	Cable set system bus	grey/black
1 x	Set of cables 24 VDC	brown/blue
2 x	Screws	M4 x 20, Phillips head



#### Field of use

Internal interface for connecting a decentralised frequency inverter (NORDAC *BASE*, NORDAC *FLEX*, NORDAC *LINK*) to the **Industrial Ethernet** (EtherCAT, PROFINET IO and EtherNet/IP). It is connected with the frequency inverter via the system bus and can directly control up to four frequency inverters. Two digital inputs are available.

Technical Information / Datasheet	SK	CU4-ET	Н	
Industrial Ethernet Module	TI 275271027	V 1.4	4123	en



### **Technical data**

### Bus interface

Temperature range	-30 °C +40 °C
Temperature class	Class 3k3
Protection class	IP20

Vibration resistance	2M4
Supply voltage	24 V ± 20%, ≈ 100 mA
	Polarity protected

Digital input - Operating range	Low: 0 V 5 V, High: 15 V 30 V
Digital input - Specific data	$R_i$ = 10 k $\Omega$ , Input capacitance: 10 nF, Response time
	1 ms, Inputs according to EN 61131-2 Type 1

### Bus specification

EtherCAT	max. 100 Mbaud
EtherNet/IP	electrical isolation 500 V <sub>eff</sub>
PROFINET IO	
Bus connection	screw terminals
Bus termination	carried out automatically
Status display	6 LED
Topology	star, tree, ring, line

Cable	min. Ethernet CAT-5
max. cable length	100 m between two Ethernet participants
Shield	directly on PE
PE port	via PE screw terminal in connection box

### Power

Parameter read access to frequency inverter	≈ 12 ms
Parameter write access with saving in EEPROM	≈ 25 ms

# Features of the bus interface when using EtherCAT

Parameterisation	via CoE (CANopen over EtherCAT)
Error messages (emergency messages)	according to CiA 301
Identification (Hot-Connect)	Configured Station Alias (via bus interface parameter) or Explicit Device Identification (via DIP switch or bus interface parameter)
Distributed Clocks	are not supported
Access for NORD diagnosis tool	see section "Parameter access and diagnosis"
Firmware update	via File Access over EtherCAT (FoE)



# Features of the bus interface when using EtherNet/IP

Transport Class: Class 1 Trigger Mode: cyclic O → T [O (Originator/Master) → T (Target/Slave)] fixed/variable size supported Real time transfer format: 32-bit run/fidle header Connection Type: Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/fidle header Connection Type: Multicast, Point2Point Priority: Scheduled 2. Listen Only Transport Class: Class 1 Trigger Mode: cyclic O → T [O (Originator/Master) → T (Target/Slave)] fixed size supported Real time transfer format: Heartbeat Connection Type: Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/fidle header Connection Type: Multicast Priority: Scheduled 3. Input Only Transport Class: Class 1 Trigger Mode: cyclic O → T [O (Originator/Master) → T (Target/Slave)] fixed size supported Real time transfer format: Heartbeat Connection Type: Multicast Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: Heartbeat Connection Type: Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/fidle header Connection Type: Multicast, Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/fidle header Connection Type: Multicast, Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/fidle header Connection Type: Multicast, Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/fidle header Connection Type: Multicast, Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer		
2. Listen Only Transport Class: Class 1 Trigger Mode: cyclic  O → T [O (Originator/Master) → T (Target/Slave)] fixed size supported Real time transfer format: Heartbeat Connection Type: Point2Point Priority: Scheduled  T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/idle header Connection Type: Multicast Priority: Scheduled  3. Input Only Transport Class: Class 1 Trigger Mode: cyclic O → T [O (Originator/Master) → T (Target/Slave)] fixed size supported Real time transfer format: Heartbeat Connection Type: Point2Point Priority: Scheduled T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/idle header Connection Type: Multicast, Point2Point Priority: Scheduled  Explicit Messages  yes  UCMM is supported  DLR is supported  DLR  Addressing  DIP switch (last byte of IP address), bus interface parameter, BOOTP (default) and DHCP possible see section "Parameter access and diagnosis", or via Ethernet (TCP)	Implicit Messages (process data connections)	Trigger Mode: cyclic  O → T [O (Originator/Master) → T (Target/Slave)] fixed/variable size supported Real time transfer format: 32-bit run/idle header Connection Type: Point2Point Priority: Scheduled  T → O [T (Target/Slave) → O (Originator/Master)] fixed/variable size supported Real time transfer format: 32-bit run/idle header Connection Type: Multicast, Point2Point
Priority: Scheduled  Explicit Messages  UCMM  is supported  DLR  is supported  DIP switch (last byte of IP address), bus interface parameter, BOOTP (default) and DHCP possible  Access for NORD diagnosis tool  see section "Parameter access and diagnosis", or via Ethernet (TCP)		<ul> <li>2. Listen Only     Transport Class: Class 1     Trigger Mode: cyclic     O → T [O (Originator/Master) → T (Target/Slave)]     fixed size supported     Real time transfer format: Heartbeat     Connection Type: Point2Point     Priority: Scheduled     T → O [T (Target/Slave) → O (Originator/Master)]     fixed/variable size supported     Real time transfer format: 32-bit run/idle header     Connection Type: Multicast     Priority: Scheduled   </li> <li>3. Input Only     Transport Class: Class 1     Trigger Mode: cyclic     O → T [O (Originator/Master) → T (Target/Slave)]     fixed size supported     Real time transfer format: Heartbeat     Connection Type: Point2Point     Priority: Scheduled     T → O [T (Target/Slave) → O (Originator/Master)]     fixed/variable size supported     Real time transfer format: 32-bit run/idle header</li> </ul>
UCMM is supported  DLR is supported  Addressing DIP switch (last byte of IP address), bus interface parameter, BOOTP (default) and DHCP possible  Access for NORD diagnosis tool see section "Parameter access and diagnosis", or via Ethernet (TCP)		
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parameter, BOOTP (default) and DHCP possible  Access for NORD diagnosis tool see section "Parameter access and diagnosis", or via Ethernet (TCP)	DLR	is supported
Ethernet (TCP)	Addressing	parameter, BOOTP (default) and DHCP possible
Firmware undate via NOPDCON coftware (TCD)	Access for NORD diagnosis tool	
Vid NORDCON Sollwale (1 CF)	Firmware update	via NORDCON software (TCP)

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# Features of the bus interface when using PROFINET IO

Communication	RT within an RT or within an IRT network
	Meaning of RT / IRT
	RT (Real Time)
	→ Real-time communication for process data
	IRT (Isochronous Real Time)
	→ Isochronous real-time communication for synchronised process data
PROFINET IO addressing	automatic address allocation via IO controller with DCP
·	(Discovery Configuration Protocol)
Data transfer	via Switched Ethernet
Auto negotiation	negotiation of transfer parameters
Auto crossover	transmission and reception cable may be crossed
	automatically in the switch
Conformance classes	CC-B and CC-C
Access for NORD diagnosis tool	see section "Parameter access and diagnosis", or via
, and the second	Ethernet (TCP)
Firmware update	via NORDCON software (TCP)

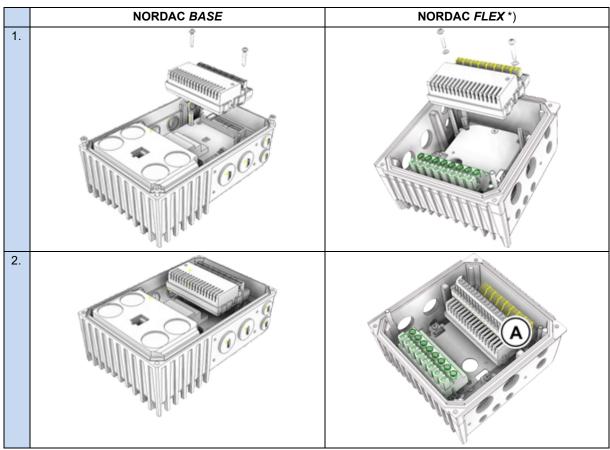


### Installation

Installation location	In defined option slot inside the NORDAC device.
Fastening	with screw fastenings

With NORDAC LINK, this assembly must be selected when ordering. The installation is then carried out at the factory. Subsequent installation is not possible.

### Installation steps



Before carrying out installation step 1 it may be necessary to remove the control terminal bar ( A ), The control terminal bar ( A ) must be fitted after installation step 2.

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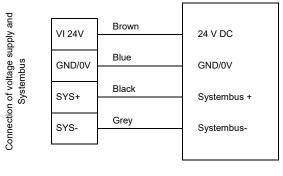


### Connections

Connection is established via terminal strips of the bus interface.

Pot	tential	Contact	Name	Description		
		E8	PHY1 RX-	Ethernet connection 2 Receive Data -		
		E7	PHY1 RX+	Ethernet connection 2 Receive Data +	Out	
		E6	PHY1 TX-	Ethernet connection 2 Transmission Data -	Out	
	Ethernet	E5	PHY1 TX+	Ethernet connection 2 Transmission Data +		
_	Ethe	E4	PHY0 RX-	Ethernet connection 1 Receive Data -		
		E3	PHY0 RX+	Ethernet connection 1 Receive Data +	In	
		E2	PHY0 TX-	Ethernet connection 1 Transmission Data -	""	
		E1	PHY0 TX+	Ethernet connection 1 Transmission Data +		
	uts	78	SYS -	System bus data cable -		(1) (2)
	System bus level and digital inputs	77	SYS+	System bus data cable +		E8 E1/78 44
		C1	DIN1	Digital input 1		
		C2	DIN2	Digital input 2		
2	evel	40	GND/0V	Reference potential (0 V/GND)		
	) snc	44	24 V	Supply potential (+24 V)		
	tem	40	GND/0V	Reference potential (0 V/GND)		
	Sys	44	24 V	Supply potential (+24 V)		

### Connection example



bus module frequency inverter



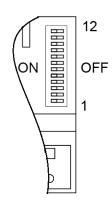
### Configuration

Configuration of the bus interface is via DIP switches, but can also be performed via the parameter settings.

DIP switch positions are read after a "Power On" of the bus interface.

Configuration via DIP switch has priority over configuration via parameter settings.

Depending on the selected dialect, some DIP switches are without function. Details can be found below the following table.



DIP switch factory setting: **OFF** 

	DIP switch											Meaning
12	11	10	9	8	7	6	5	4	3	2	1	Address
			0	0	0	0	0	0	0	0		0
			0	0	0	0	0	0	0	1		1
			0	0	0	0	0	0	1	0		2
						:		:				
			1	1	1	1	1	1	1	1		255
											0	Terminating resistor system bus (not set)
											1	Terminating resistor system bus (set)
		0										TCP rights (function see below)
		1										TCP rights (function see below)
0	0	Ethernet protocol (dialect) selection via parameter P899										
0	1	PROFINET IO										
1	0	EtherCAT										
1	1				EtherNet/IP							

Mea	Meaning of symbols				
0	DIP switch in "OFF" position				
1	DIP switch in "ON" position				

DIP 1	DIP 1					
Terminating res	Terminating resistor system bus					
PROFINET IO	The system bus must be terminated with a terminating resistor at its two physicals ends. If					
EtherCAT	bus interface is at the end of the system bus, the DIP 1 switch must be set to "ON".					
EtherNet/IP						

DIP 29	
Address	
PROFINET IO	No function.  • The address is set via parameter <b>P850</b> .
EtherCAT	<ul> <li>Setting the "Explicit Device Identification".</li> <li>For switch position "OFF": The address is set via parameter P850.</li> <li>If the Second Address is set via DIP switch, it cannot be controlled via the NORD parameters.</li> </ul>
EtherNet/IP	<ul> <li>Setting the last byte of the IP address.</li> <li>For switch position "OFF": The address is set via parameter P850. Additionally: Set parameter P856 to setting "0" ("Address via P850").</li> <li>The set IP address can be controlled via parameter P875.</li> </ul>

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DIP 10 TCP rights	NOTICE! Observe the functions specified below for setting the DIP switches!
PROFINET IO	No function.
	The TCP rights are configured via the parameter <b>P853</b> .
EtherCAT	Activating the FoE functionality for firmware updates.
	<ul><li>"OFF" = Write and read permissions</li></ul>
	<ul><li>– "ON" = Read-only permissions</li></ul>
	The TCP rights are configured via the parameter P853.
EtherNet/IP	Activating the TCP functionality.
	<ul> <li>"OFF" = TCP ON, the TCP rights are configured via the parameter P853.</li> </ul>
	- "ON" = TCP Off (configuration of the TCP rights via the parameter P853 has no
	effect.)

DIP 1112	DIP 1112 Ethernet protocol (dialect)					
PROFINET IO This DIP switch determines the used Ethernet protocol. In the DIP 11 = 0 and DIP 12						
EtherCAT	combination, the protocol can be switched via parameter <b>P899</b> ( BU 2900).					
EtherNet/IP						



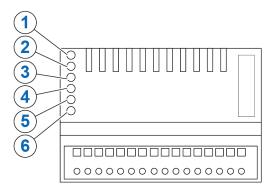
### NORDAC LINK

With the NORDAC *LINK*, the DIP switch settings can only be adjusted at the factory. Subsequent adaptation is not possible. The configuration of the module must therefore be defined when ordering.

#### **LED** indicators

Visualisation of operating statuses of the bus interface is done via LED indicators.

No.	Name	Colour
1	RUN/MS	Dual (red/green)
2	ERR/NS	Dual (red/green)
3	L/A1	Dual (green/yellow)
4	L/A2	Dual (green/yellow)
5	DEV	Dual (red/green)
6	BUS	Dual (red/green)



### LED L/A1, L/A2

LEDs labelled "L/A" (Link/Activity) indicate the status of the Internet interface.

L/A	Meaning
Off	No Ethernet connection (check cable connection)
Green on and yellow flashing (4 Hz)	Ethernet connection is established and data is being transmitted
Green on	Ethernet connection is established. No data is being transmitted.



### NORD-specific LED

The LED labelled "DEV" indicates the general device status.

DEV	Meaning
Green on	Module is ok
Green on and red flashing (1 Hz)	Frequency inverter in fault state
Green and red on	Frequency inverter in update mode
Red and green flashing simultaneously	Update files are transmitted via Ethernet

### The LED labelled "BUS" indicates the status of communication at system bus level.

BUS	Meaning
Off	No supply voltage
Green on	Process data communication active, or frequency inverter's firmware update
Green flashing (2 Hz)	No system bus frequency inverter available
Red and green flashing alternately (4 Hz)	System bus in status "BUS Warning" because     no further CAN participant exists.     the CAN controller is in "Error Passive" state.     an EMC interference is present.
Red on	System bus in state "BUS-OFF"

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# EtherCAT-specific LED

RUN	State	Meaning
Off	Init	No communication of process data and parameters
Green flashing (4 Hz)	Pre-Operational	Parameter communication active     No process data communication
Green single flash	Save Operational	<ul> <li>Parameter communication active</li> <li>Restricted process data communication</li> <li>No restrictions to actual values</li> <li>Setpoints not evaluated</li> </ul>
Green On	Operational	Parameter communication active     Unrestricted parameter communication active

ERR	State	Meaning
Off	No Error	EtherCAT functioning normally on the bus interface
Red flashing (4 Hz)	Invalid Configuration	General EtherCAT configuration error,     may be generated because of an incorrect XML file
Red single flash	Unsolicited State Change	Bus interface has changed the EtherCAT state without authorisation
Red double flash	Application Watchdog Timeout	EtherCAT or FI timeout (P513 or P151)

### EtherNet/IP-specific LED

MS	Meaning
Off	No mains or control voltage
Green On	Bus interface working correctly
Green flashing (4 Hz)	Bus interface not configured
Red flashing (4 Hz)	Minor errors, faulty configuration
Red and Green flashing alternately (4 Hz)	Power-up, self test

NS	Meaning
Off	No mains or control voltage
Green On	CIP connection available
Green flashing (4 Hz)	IP address configured but no CIP connection available
Red flashing (4 Hz)	Time-out
	An "exclusive owner connection" has a timeout error
Red and Green flashing alternately (4 Hz)	Power-up, self test
Red On	Double IP
	IP address used by the bus interface is used already.



#### PROFINET IO-specific LED

RUN		Meaning
Off	•	No error
Red flashing (1 Hz)	•	DCP signal is triggered via the bus.
Red on	•	System error / alarm

ERR	Meaning
Off	No errors
Red flashing (2 Hz)	No data exchange
Red on	No configuration or no physical connection

#### Parameter access and diagnosis

The NORDCON software from version 2.9.1 and higher or optional control units such as the SK PAR-3H ParameterBox provide convenient access to the parameters of the bus interface and allow status information to be read out. In addition, the NORDCON *APP* — in connection with the NORDAC *ACCESS BT* Bluetooth stick — offers a practical way of mobile and wireless maintenance as well as commissioning of NORD frequency inverters.

Access is via the RJ12 diagnostics socket of the frequency inverter. The prerequisite for this is that the bus interface is connected to the frequency inverter via the system bus.

When using EtherNet/IP and PROFINET IO, access is also possible via Ethernet (TCP). This is based on the prerequisite that IP addresses have been set and the necessary rights have been granted.

#### Further documentation and software (www.nord.com)

Software	Description
Device description files	Device characteristics and
	parameters

Document	Description
BU 0000	Description of NORDCON software
BU 0040	Parameter box manual
BU 0180	Manual for NORDAC BASE frequency inverters
<u>BU 0200</u>	Manual for NORDAC FLEX frequency inverters

Software	Description
NORDCON	Parameterisation and diagnostic software

Document	Description
<u>TI 275274505</u>	SK TIE4-M12-SYSM System bus output connection extension
<u>TI 275274506</u>	SK TIE4-M12-SYSS System bus input connection extension
TI 275274514	SK TIE4-M12-ETH Ethernet input/output connection extension
BU 0250	Manual for the NORDAC LINK frequency inverter
<u>BU 2900</u>	Manual for Industrial Ethernet bus communication

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